

# Automatic sequences are orthogonal to aperiodic multiplicative functions

Clemens Müllner



Tuesday, November 27, 2018

# Multiplicative functions

## Definition (multiplicative function)

A function  $f : \mathbb{N} \rightarrow \mathbb{C}$  is called *multiplicative* if  $f(nm) = f(n)f(m)$  for all  $n, m$  that are coprime.

The Möbius function is defined by

$$\mu(n) = \begin{cases} (-1)^k & \text{if } n \text{ is squarefree and} \\ & k \text{ is the number of prime factors} \\ 0 & \text{otherwise} \end{cases}$$

Two bounded sequences  $\mathbf{u}, \mathbf{v}$  are *orthogonal* if

$$\sum_{n \leq N} u_n \overline{v_n} = o(N) \quad (N \rightarrow \infty).$$

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# Sarnak Conjecture

## Definition

A dynamical system is said to be deterministic, if its topological entropy is 0.

## Conjecture (Sarnak conjecture, 2010)

Every bounded complex sequence  $\mathbf{u} = (u_n)_{n>0}$  that is obtained by a deterministic dynamical system is orthogonal to the Möbius function  $\mu(n)$ .

# Sarnak Conjecture

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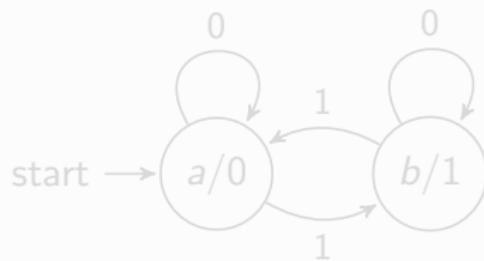
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# Deterministic Finite Automata

## Definition (Automaton - DFA)

$$A = (Q, \Sigma = \{0, \dots, k-1\}, \delta, q_0, \tau)$$

## Example (Thue-Morse sequence)



$$n = 22 = (10110)_2, \quad u_{22} = 1$$

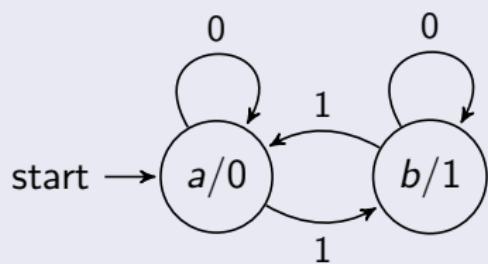
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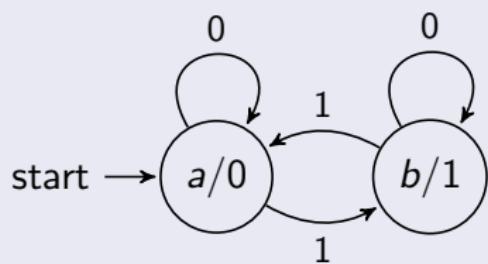
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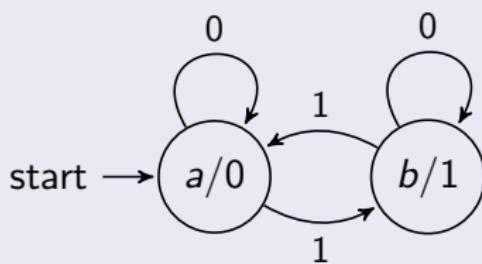
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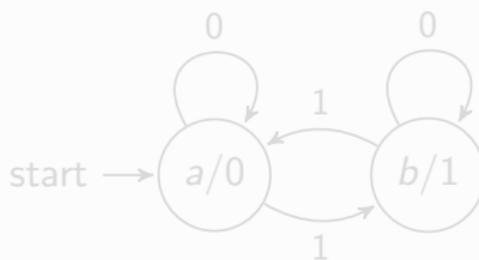
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## Automaton



## Substitution

Coding of the fixpoint of a substitution:

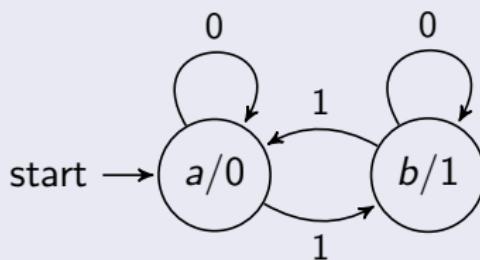
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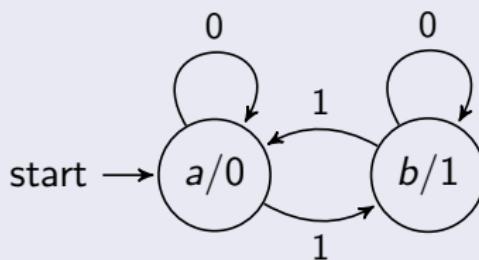
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# Substitutions

## Definition (Substitution of constant length)

Let  $\mathbb{A}$  be a finite set. Then we call  $\theta : \mathbb{A} \rightarrow \mathbb{A}^\lambda$  a *substitution of length  $\lambda$* .

We write  $\theta(a) = \theta(a)_0 \dots \theta(a)_{\lambda-1}$ . We extend  $\theta$  to finite blocks and infinite sequences by concatenation.

$$\theta(b_1 \dots b_r) = \theta(b_1) \dots \theta(b_r).$$

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## Example

$$a \xrightarrow{\theta} aba \xrightarrow{\theta} ababacaba$$

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Every automatic sequence  $(a_n)_{n \geq 0}$  fulfills the Sarnak Conjecture

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Every bijective automatic sequence is orthogonal to every aperiodic bounded multiplicative function.

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## Naive Question

Why not all bounded multiplicative functions?

Trivial counter-example: periodic sequences.

Non-trivial counter-example:  $a(n) = (-1)^{\nu_2(n)}$ .

## Definition (aperiodic sequence)

We call a sequence  $\mathbf{u}$  aperiodic if for all  $k, \ell \in \mathbb{N}$

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# Dynamical Systems

$$X_\theta := \{x \in \mathbb{A}^{\mathbb{Z}} : \forall r < s \ \exists a \in \mathbb{A}, k, j \in \mathbb{N} : \\ x[r, s] = \theta^k(a)[j, j + s - r + 1]\}$$

Shift  $T : \mathbb{A}^{\mathbb{Z}} \rightarrow \mathbb{A}^{\mathbb{Z}}$ ,  $T(x)[n] = x[n + 1]$ .

This gives a dynamical system  $(X_\theta, T)$ .

## Proposition (Michel; Dekking)

Let  $\theta$  be a primitive substitution of length  $\lambda$ . Then there exists a unique measure  $\mu_\theta$  such that  $(X_\theta, T, \mu_\theta)$  is ergodic. Furthermore,  $(X_\theta, T, \mu_\theta)$  is minimal.

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Let  $u$  be a one-sided fixed-point of  $\theta$ . We define the height to be the maximal  $h$ , coprime to  $\lambda$  such that we can partition  $\mathbb{A}$  into  $h$  classes, so that the resulting sequence is  $h$ -periodic.

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## Lemma (Lemanczyk, M.)

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# Structure of $(X_\theta, T)$

## Theorem

Let  $\theta$  be a primitive substitution of length  $\lambda$  and  $X_\theta$  be infinite. Then for each  $k \in \mathbb{N}$ ,  $x \in X_\theta$  there exists a unique  $j < \lambda^k$ ,  $y \in X_\theta$  such that

$$x = T^j \theta^k(y).$$

Example:

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This way we can assign to each  $x \in X_\theta$  a sequence  $(j_k)_{k \in \mathbb{N}}$ , where  $j_k \in \{0, \dots, \lambda^k - 1\}$  and  $j_{k+1} \equiv j_k \pmod{\lambda^k}$ .

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# The $\lambda$ Odometer

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$$H_\lambda := \liminf \mathbb{Z}/\lambda^k \mathbb{Z}.$$

$H_\lambda \ni x = (j_k)_{k \in \mathbb{N}}$ , where  $j_{k+1} \equiv j_k \pmod{\lambda^k}$ .

$$R : H_\lambda \rightarrow H_\lambda$$

$$R((j_k)_{k \in \mathbb{N}}) = (j_k + 1)_{k \in \mathbb{N}}.$$

$(H_\lambda, R)$  is a uniquely ergodic system with discrete spectrum, i.e.  
 $L^2(H_\lambda, R, \mu)$  is spanned by eigenfunctions of the unitary operator  
 $U_R : f \rightarrow f \circ R$  on  $L^2(H_\lambda, R, \mu)$ .

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$H_\lambda \ni x = (j_k)_{k \in \mathbb{N}}$ , where  $j_{k+1} \equiv j_k \pmod{\lambda^k}$ .

$$R : H_\lambda \rightarrow H_\lambda$$

$$R((j_k)_{k \in \mathbb{N}}) = (j_k + 1)_{k \in \mathbb{N}}.$$

$(H_\lambda, R)$  is a uniquely ergodic system with discrete spectrum, i.e.  
 $L^2(H_\lambda, R, \mu)$  is spanned by eigenfunctions of the unitary operator  
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# $H_\lambda$ as a factor of $X_\theta$

We see that

$$\pi_\theta : x \mapsto (j_k)_{k \in \mathbb{N}},$$

settles a map from  $(X_\theta, T)$  to  $(H_\lambda, R)$ .

## Theorem (Dekking)

Let  $\theta$  be primitive and  $h(\theta) = 1$ . The map  $\pi_\theta$  is  $c(\theta)$ -to-1 almost everywhere.

In this case we have that  $H_\lambda$  is the Kronecker factor of  $X_\theta$ , i.e. the largest factor with discrete spectrum.

## Corollary

If  $c(\theta) = 1$ , then  $(X_\theta, T) \cong (H_\lambda, R)$  measure-theoretically.

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# The synchronizing part of a substitution

Let  $\theta : \mathbb{A} \rightarrow \mathbb{A}^\lambda$ .

We denote by  $\mathcal{X}$  the set of „minimal columns“,

$$\mathcal{X} := \{M \subset \mathbb{A} : |M| = c(\theta), \exists k, j : \theta^k(\mathbb{A})_j = M\}.$$

Example:

$$a \xrightarrow{\theta} aba \xrightarrow{\theta} ababacaba$$

$$b \xrightarrow{\theta} bac \xrightarrow{\theta} bacabacab$$

$$c \xrightarrow{\theta} cab \xrightarrow{\theta} cabababac$$

$$\mathcal{X} = \{\{a, b\}, \{a, c\}\}.$$

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$$a \xrightarrow{\theta} a b a \xrightarrow{\theta} a b a b a c a b a$$

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$$a \xrightarrow{\theta} a b a \xrightarrow{\theta} a \textcolor{red}{b} a b a \textcolor{red}{c} a b a$$

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# The synchronizing part of a substitution

We define  $\tilde{\theta} : \mathcal{X} \rightarrow \mathcal{X}^\lambda$ :

$$\tilde{\theta}(M)_j = \theta(M)_j.$$

Example:

$$R := \{a, b\}, S := \{a, c\},$$

$$a \xrightarrow{\theta} aba$$

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$$R \xrightarrow{\tilde{\theta}} RRS$$

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# Joining $\theta$ and $\tilde{\theta}$

We consider  $\mathcal{A} \subset \mathbb{A} \times \mathcal{X}$ :

$$\mathcal{A} := \{(a, M) \in \mathbb{A} \times \mathcal{X} : a \in M\}.$$

$$\Theta : \mathcal{A} \rightarrow \mathcal{A}^\lambda,$$

$$\Theta((a, M))_j := (\theta(a)_j, \tilde{\theta}(M)_j).$$

We consider now  $X_\Theta$  and find projections

$$\pi_1 : X_\Theta \rightarrow X_\theta, \pi_2 : X_\Theta \rightarrow X_{\tilde{\theta}}:$$

$$\pi_1((x[n], M[n])_{n \in \mathbb{Z}}) = (x[n])_{n \in \mathbb{Z}},$$

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# Example continued

$R := \{a, b\}, S := \{a, c\},$

$$a \xrightarrow{\theta} a b a$$

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$$c \xrightarrow{\theta} c a b$$

$$R \xrightarrow{\tilde{\theta}} R R S$$

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$$(a, R) \xrightarrow{\Theta} (a, R)(b, R)(a, S)$$

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# How different are $X_\theta$ and $X_\Theta$ ?

## Lemma

If  $\theta$  is primitive, then so is  $\Theta$  and furthermore:

$$c(\theta) = c(\Theta)$$

$$h(\theta) = h(\Theta).$$

Let us consider a generic point  $z \in H_\lambda$ :

$$\pi_\theta^{-1}(z) = \{(x^{(i)}[n])_{n \in \mathbb{Z}} : i = 1, \dots, c\}$$

$$\pi_{\tilde{\theta}}^{-1}(z) = (M[n])_{n \in \mathbb{Z}}$$

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# Renaming the alphabet of $\Theta$

We see that  $\Theta(., M)_j$  is a bijection from  $M$  to  $\tilde{\theta}(M)_j$ .

We rename our alphabet:  $(a, M) \rightarrow (i, M)$  where  $i \in \{1, \dots, c\}$ .

Example:

$$\begin{array}{ll} (a, R) \mapsto (1, R) & (b, R) \mapsto (2, R) \\ (a, S) \mapsto (1, S) & (c, S) \mapsto (2, S) \end{array}$$

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# Towards a group extension

$\tilde{\Theta}(., M)_j$  is a bijection from  $\{1, \dots, c\}$  to itself.

$\sigma_{M,j} \in S_c, \sigma_{M,j}(m) = n$  iff  $\tilde{\Theta}(n, M)_j = (m, \tilde{\theta}(M)_j)$ .

$G := < \sigma_{M,j} : M \in \mathcal{X}, j \in \{1, \dots, c\} >$ .

$\widehat{\Theta} : (G \times \mathcal{X}) \rightarrow (G \times \mathcal{X})^\lambda$ ,

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# New Example

$$a \xrightarrow{\theta} a b b$$

$$b \xrightarrow{\theta} b a c$$

$$c \xrightarrow{\theta} c d a$$

$$d \xrightarrow{\theta} d d a.$$

$$\mathcal{X} = \{\{a, b, c\}, \{a, b, d\}\} = \{R, S\}.$$

$$R \xrightarrow{\tilde{\theta}} R S R$$

$$S \xrightarrow{\tilde{\theta}} S S R.$$

$$(1, R) \xrightarrow{\tilde{\Theta}} (1, R) (2, S) (2, R)$$

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# Example continued

$$(1, R) \xrightarrow{\tilde{\Theta}} (1, R)(2, S)(2, R)$$

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$$\sigma_{R,0} = (1) \quad \sigma_{S,0} = (1)$$

$$\sigma_{R,1} = (12) \quad \sigma_{S,1} = (12)$$

$$\sigma_{R,2} = (132) \quad \sigma_{S,2} = (132).$$

# Example continued

$$\begin{array}{ll}
 (1, R) \xrightarrow{\tilde{\Theta}} (1, R)(2, S)(2, R) & (1, S) \xrightarrow{\tilde{\Theta}} (1, S)(2, S)(2, R) \\
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If  $\theta$  is primitive, then so is  $\widehat{\Theta}$ .  $X_\theta$  is a topological factor of  $X_{\widehat{\Theta}}$ .

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# Group extensions

## Definition (compact group extension)

Given  $(X, T, \mu)$  and  $\phi : X \rightarrow G$  measurable. Then we call  $(X \times G, T_\phi, \mu \otimes m_G)$  a compact group extension, where

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# General Plan

We build successively bigger dynamical systems

$$X_\theta \hookrightarrow X_\Theta = X_{\tilde{\Theta}} \hookrightarrow X_{\widehat{\Theta}}.$$

We want to show that

$$\lim_{N \rightarrow \infty} \frac{1}{N} \sum_{n \leq N} F(T^n(x))m(n) = 0,$$

where  $x \in X_{\widehat{\Theta}}$ ,  $F \in C(\widehat{\Theta}, \mathbb{C})$ .

We write  $F = F_d + F_c$  where  $F_d \in L^2(H_\lambda, R)$  and continuous, and  $F_c$  is orthogonal to  $L^2(H_\lambda, R)$ .

$F_d$  can be approximated by periodic functions and is hence orthogonal to aperiodic functions.

For  $F_c$ , we use the Katai Criterion.

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# Key Tool

## Katai Criterion

Suppose that for all but finitely many  $p, q \in \mathbb{P}$  we have

$$\sum_{n \leq N} a(pn) \overline{a(qn)} = o(N).$$

Then we have for all multiplicative bounded functions  $m : \mathbb{N} \rightarrow \mathbb{N}$ ,

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By a series of results on group extensions of  $H_\lambda$  we find that the only such joinings are relatively independent extensions over the isomorphism  $W$  between  $R^p$  and  $R^q$ , i.e.

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